

Class Exercise 2 - The Dirac delta function

The delta-function is a generalized function. It can be thought of as the limit of a series of functions which become increasingly tall and narrow, with the following defining properties:

$$1. \delta(x) = \begin{cases} \infty & x = 0 \\ 0 & x \neq 0 \end{cases}$$

$$2. \int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$3. \int_{-\infty}^{\infty} \delta(x - x_0) f(x) dx = f(x_0)$$

Note that the integral property applies to any choice of bounds which contain the point $x = 0$. The generic form of this property could be written as

$$\int_{x_0 - \varepsilon}^{x_0 + \varepsilon} \delta(x - x_0) dx = 1,$$

for any $\varepsilon > 0$.

The delta-function is used to sample quantities, such as charge density, for example a single point charge q located at x_0 has a charge density of

$$\rho(x) = q\delta(x - x_0).$$

Using the superposition principle, we can write the charge density of N such point charges. For example, in $3d$ we have

$$\rho(\vec{r}) = \sum_{i=1}^N q_i \delta^{(3)}(\vec{r} - \vec{r}_i).$$

There are many examples of functions with a limiting behavior of a delta-function:

- Lorentzian - $f(x) = \frac{1}{\pi} \frac{\epsilon}{x^2 + \epsilon^2}$,
- Gaussian - $f(x) = \frac{1}{\epsilon\sqrt{\pi}} \exp(-x^2/\epsilon^2)$,

- Sinc - $f(x) = \frac{1}{\pi} \frac{\sin(x/\epsilon)}{x}$.

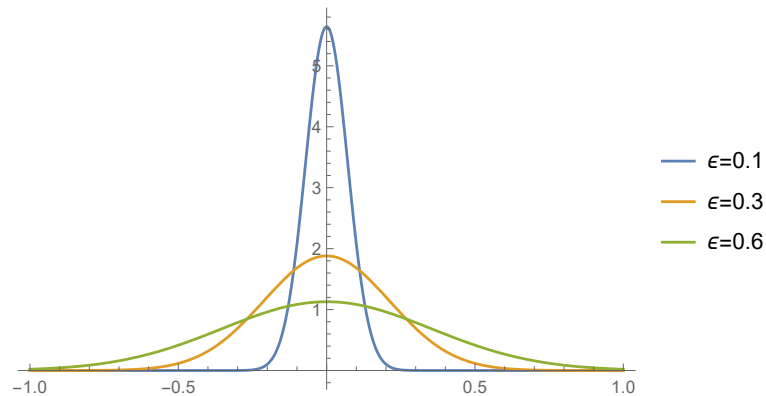


Fig. 1: The Gaussian $f(x) = \frac{1}{\epsilon\sqrt{\pi}} \exp(-x^2/\epsilon^2)$ for decreasingly small values of ϵ tends to a delta-function.

It is straightforward to check that taking $\epsilon \rightarrow 0$ gives a delta function in each of these cases. Some additional properties of the delta-function include

- $\delta(x) = \delta(-x)$,
- $\delta(\alpha x) = \frac{1}{|\alpha|} \delta(x)$
- $\delta(g(x)) = \sum_i \frac{\delta(x-x_i)}{|g'(x_i)|}$

Another useful function is the Heaviside function (a.k.a the “step” function), defined as

$$\Theta(x) = \begin{cases} 1, & x > 0, \\ 0, & x < 0. \end{cases}$$

It can be shown that

$$\Theta'(x) = \delta(x).$$

Problem 1

Prove the relation

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikx}. \quad (1)$$

Solution:

To perform the integration, we use the common trick of adding an ε contribution to the integral (which we will ultimately set to zero when we are done) in the following way:

$$\int_{-\infty}^{\infty} dk e^{ikx} = \int_{-\infty}^0 dk e^{ikx} + \int_0^{\infty} dk e^{ikx} = \lim_{\varepsilon \rightarrow 0^+} \left(\int_{-\infty}^0 dk e^{ik(x-i\varepsilon)} + \int_0^{\infty} dk e^{ik(x+i\varepsilon)} \right). \quad (2)$$

The integration is carried before taking the limit,

$$\begin{aligned} \int_{-\infty}^{\infty} dk e^{ikx} &= \lim_{\varepsilon \rightarrow 0^+} \left(\left. \frac{e^{ik(x-i\varepsilon)}}{i(x-i\varepsilon)} \right|_{k=-\infty}^0 + \left. \frac{e^{ik(x+i\varepsilon)}}{i(x+i\varepsilon)} \right|_{k=0}^{\infty} \right) \\ &= \lim_{\varepsilon \rightarrow 0^+} \left(\frac{1}{i(x-i\varepsilon)} - \frac{1}{i(x+i\varepsilon)} - \lim_{k \rightarrow \infty} \underbrace{e^{-k\varepsilon}}_{\text{tends to zero}} \left[\overbrace{\frac{e^{-ikx}}{i(x-i\varepsilon)} + \frac{e^{ikx}}{i(x+i\varepsilon)}}^{\text{oscillates in bounded region}} \right] \right) \\ &= \lim_{\varepsilon \rightarrow 0^+} \left(\frac{1}{i(x-i\varepsilon)} - \frac{1}{i(x+i\varepsilon)} \right) \\ &= \lim_{\varepsilon \rightarrow 0^+} \left(\frac{x+i\varepsilon}{i(x^2+\varepsilon^2)} - \frac{x-i\varepsilon}{i(x^2+\varepsilon^2)} \right) \\ &= \lim_{\varepsilon \rightarrow 0^+} \frac{2\varepsilon}{x^2+\varepsilon^2} = 2\pi\delta(x), \end{aligned} \quad (3)$$

where in the last line we used the Lorentzian limit of the delta function that you saw in class.

Problem 2

Recall that in Cartesian coordinates,

$$\delta^{(D)}(\mathbf{x} - \mathbf{x}_0) = \prod_{i=1}^D \delta(x_i) = \delta(x_1) \delta(x_2) \cdots \delta(x_D). \quad (4)$$

Find the delta function $\delta^{(3)}(\mathbf{x} - \mathbf{x}_0)$ in spherical coordinates and cylindrical coordinates.

Solution

Recall the multidimensional property (or definition) of the delta function

$$\int \dots \int d^D x \delta^{(D)}(\mathbf{x}) = 1. \quad (5)$$

Hence, in Cartesian coordinates we have

$$\int \dots \int d^D x \delta^{(D)}(\mathbf{x}) = \prod_{i=1}^D \int dx_i \delta(x_i). \quad (6)$$

In 3d spherical coordinates, we know that the volume element is $r^2 \sin \theta dr d\theta d\varphi$, and we therefore have that

$$\int dr \int d\theta \int d\varphi r^2 \sin \theta \delta^{(3)}(\vec{r} - \vec{r}_0) = 1. \quad (7)$$

Indeed, to obtain a form similar to (5) (and with proper units of density!), we need to have

$$r^2 \sin \theta \delta^{(3)}(\vec{r} - \vec{r}_0) = \delta(r - r_0) \delta(\theta - \theta_0) \delta(\varphi - \varphi_0), \quad (8)$$

and thus in spherical coordinates,

$$\delta^{(3)}(\vec{r} - \vec{r}_0) = \frac{1}{r^2 \sin \theta} \delta(r - r_0) \delta(\theta - \theta_0) \delta(\varphi - \varphi_0). \quad (9)$$

In cylindrical coordinates, the volume element is $r dr d\theta dz$, and we similarly find

$$\delta^{(3)}(\vec{r} - \vec{r}_0) = \frac{1}{r} \delta(r - r_0) \delta(\theta - \theta_0) \delta(z - z_0). \quad (10)$$

Problem 3

Express the following charge densities using δ functions in the appropriate coordinates:

1. N point charge with different charges q_i and positions z_i on the $\hat{\mathbf{z}}$ axis.
2. Total charge Q uniformly distributed over a sphere with radius R .
3. Thin disk of radius R and total charge Q , located in the $x - y$ plane.

Solution

1. The charges are distributed over the $\hat{\mathbf{z}}$ axis, and are thus positioned at $x = y = 0$. We therefore write the charge density as

$$\rho(\vec{x}) = \sum_{i=1}^N q_i \delta(x) \delta(y) \delta(z - z_i). \quad (11)$$

We can check that the total charge is correct by integration,

$$\iiint_V \rho(\vec{x}) d^3x = \iiint_V dx dy dz \sum_{i=1}^N q_i \delta(x) \delta(y) \delta(z - z_i) = \sum_{i=1}^N q_i. \quad (12)$$

2. We work in spherical coordinates. The surface charge density is

$$\sigma = \frac{Q}{4\pi R^2}, \quad (13)$$

concentrated entirely on the shell at $r = R$. We therefore have

$$\begin{aligned} \rho(\vec{r}) &= \int dq \delta^{(3)}(\vec{x} - \vec{x}') \\ &= \sigma \int_0^\pi d\theta' \int_0^{2\pi} d\varphi' R^2 \sin\theta' \frac{\delta(r - R) \delta(\theta - \theta') \delta(\varphi - \varphi')}{r^2 \sin\theta} \\ &= \sigma \int_0^\pi d\theta' \int_0^{2\pi} d\varphi' \delta(r - R) \delta(\theta - \theta') \delta(\varphi - \varphi') \\ &= \sigma \delta(r - R) \\ &= \frac{Q}{4\pi R^2} \delta(r - R). \end{aligned} \quad (14)$$

3. The surface charge density is

$$\sigma = \frac{Q}{\pi R^2}. \quad (15)$$

We work in cylindrical coordinates and integrate,

$$\begin{aligned}
\rho(\vec{r}) &= \int dq \delta^{(3)}(\vec{x} - \vec{x}') \\
&= \sigma \int_0^{2\pi} d\theta' \int_0^R dr' r' \frac{\delta(r - r') \delta(\theta - \theta') \delta(z)}{r} \\
&= \sigma \delta(z) \int_0^R dr' \delta(r - r').
\end{aligned} \tag{16}$$

We recall that

$$\frac{\partial}{\partial r} \Theta(r - r') = -\frac{\partial}{\partial r'} \Theta(r - r') = \delta(r - r'), \tag{17}$$

which means we can write

$$\rho(\vec{r}) = -\sigma \delta(z) \int_0^R dr' \frac{\partial}{\partial r'} \Theta(r - r') = \sigma \delta(z) [\Theta(r) - \Theta(r - R)]. \tag{18}$$

Note that

$$\Theta(r) - \Theta(r - R) = \Theta(R - r) = \begin{cases} 1 & 0 < r < R \\ 0 & r > R \end{cases}, \tag{19}$$

and therefore we find the charge density

$$\rho(\vec{r}) = \sigma \delta(z) \Theta(R - r) = \frac{Q}{\pi R^2} \delta(z) \Theta(R - r). \tag{20}$$

Problem 4

A thin ring of radius R is homogeneously charged with charge density λ . Find the potential on the symmetry axis of the ring, far away from the ring.

Solution

The solution to the Laplace equation is

$$\varphi(\vec{r}) = \iiint \frac{\rho(\vec{r}') d\vec{r}'}{|\vec{r} - \vec{r}'|}. \quad (21)$$

In our case, assuming the ring is located at $z = 0$, we have the charge density

$$\rho(\vec{r}') = \lambda \delta(r' - R) \delta(z'). \quad (22)$$

The chosen point of reference is somewhere on the \hat{z} axis, and therefore $\vec{r} = z\hat{z}$, and the location of the charge is $\vec{r}' = R\hat{r}$. Our integral is then

$$\begin{aligned} \varphi(\vec{r}) &= \lambda \int dr' \int d\theta' \int dz' \frac{\delta(r' - R) \delta(z') r'}{|z\hat{z} - R\hat{r}|} \\ &= \lambda \iiint \frac{\delta(r' - R) \delta(z') r' dr' d\theta' dz'}{\sqrt{z^2 + R^2}} \\ &= \lambda \int_0^{2\pi} \frac{R d\theta'}{\sqrt{z^2 + R^2}} = \frac{2\pi R \lambda}{\sqrt{z^2 + R^2}}. \end{aligned} \quad (23)$$

Far away from the ring we have $z \gg R$, and thus

$$\varphi(z) = \frac{2\pi R \lambda}{z \sqrt{1 + \left(\frac{R}{z}\right)^2}} \underset{z \gg R}{\approx} \frac{2\pi R \lambda}{z} \left(1 - \frac{1}{2} \left(\frac{R}{z}\right)^2\right). \quad (24)$$

Problem 5

Solve the 1d equation

$$\frac{d^2}{dx^2}G(x, x') = \delta(x - x'), \quad (25)$$

given the initial conditions $G(x = 0, x') = G(x = L, x') = 0$.

Solution

First, we note that for $x \neq x'$,

$$\frac{d^2}{dx^2}G(x, x') = 0. \quad (26)$$

We might be tempted to say that the general solution is a simple linear function,

$$G(x, x') = Ax + B. \quad (27)$$

Consider the derivative of this solution,

$$\frac{d}{dx}G(x, x') = A. \quad (28)$$

We will show that this does not hold for all points x :

Integrating equation (25) from $x = x' - \epsilon$ to $x = x' + \epsilon$,

$$\int_{x'-\epsilon}^{x'+\epsilon} \frac{d^2}{dx^2}G(x, x') dx = \int_{x'-\epsilon}^{x'+\epsilon} \delta(x - x') dx, \quad (29)$$

we find

$$\left. \frac{dG}{dx} \right|_{x'+\epsilon} - \left. \frac{dG}{dx} \right|_{x'-\epsilon} = 1. \quad (30)$$

Therefore, equation (27) cannot be true for all x . However, we can split the solution into a pair of different linear solutions,

$$G(x, x') = \begin{cases} Ax + B, & 0 < x < x' < L, \\ Cx + D, & 0 < x' < x < L, \end{cases} \quad (31)$$

such that these satisfy the following conditions:

$$\overbrace{G(x = x' - \epsilon, x') = G(x = x' + \epsilon, x')}^{\text{Continuity}}, \quad (32)$$

$$\overbrace{\left. \frac{dG}{dx} \right|_{x'+\epsilon} - \left. \frac{dG}{dx} \right|_{x'-\epsilon}}^{\text{Jump in 1st derivative}} = 1, \quad (33)$$

$$\overbrace{G(x=0, x')}^{\text{Boundary condition}} = 0, \quad (34)$$

$$\overbrace{G(x=L, x')}^{\text{Boundary condition}} = 0. \quad (35)$$

From equation (34) we find $B = 0$, and from equation (35) we find

$$CL + D = 0. \quad (36)$$

So far, we find that the general solution takes the form

$$G(x, x') = \begin{cases} Ax, & 0 < x < x' < L, \\ C(x - L), & 0 < x' < x < L. \end{cases} \quad (37)$$

We use the jump in the derivative (equation (33)) to determine that

$$C - A = 1, \quad (38)$$

and finally, invoke the continuity condition (32) as $\epsilon \rightarrow 0$, replace A by $C - 1$ and obtain

$$(C - 1)x' = C(x' - L) \quad (39)$$

$$\implies C = \frac{x'}{L}, \quad (39)$$

$$\implies A = \frac{x' - L}{L}. \quad (40)$$

The complete solution is then

$$G(x, x') = \begin{cases} \left(\frac{x'-L}{L}\right)x, & 0 < x < x' < L, \\ \frac{x'}{L}(x - L), & 0 < x' < x < L. \end{cases} \quad (41)$$

Problem 6

Given the electric potential function

$$\varphi(\vec{r}) = \frac{1}{r}, \quad (42)$$

find the electric field and the charge density.

Solution

The potential only depends on r (and not on the angular coordinates), so we choose to solve this problem in spherical coordinates.

We begin by calculating the electric field. Recall from Physics 2 that

$$\vec{E}(\vec{r}) = -\vec{\nabla}\varphi(\vec{r}). \quad (43)$$

Since $\varphi = \varphi(r)$, in spherical coordinates we have

$$\vec{E}(\vec{r}) = -\frac{\partial\varphi(\vec{r})}{\partial r}\hat{\mathbf{r}} = \frac{\hat{\mathbf{r}}}{r^2}. \quad (44)$$

For the field density $\rho(\vec{r})$, we take the divergence of \vec{E} (which is also the Laplacian of φ), and use the relation

$$\vec{\nabla} \cdot \vec{E} = 4\pi\rho. \quad (45)$$

Again, $\vec{E} = \vec{E}(r)$ and so we have

$$4\pi\rho(\vec{r}) = \frac{1}{r^2} \frac{\partial(r^2 E_r)}{\partial r} = \frac{1}{r^2} \frac{\partial(r^2/r^2)}{\partial r} = 0. \quad (46)$$

It appears that the divergence of the field is everywhere zero! But that is impossible - since we find that by applying Gauss' law to an integral of ball of radius r around the origin,

$$\iiint_V \vec{\nabla} \cdot \vec{E} d^3r = \oiint_{\partial V} \vec{E} \cdot \hat{\mathbf{r}} dS = \oiint_{\partial V} \left(\frac{\hat{\mathbf{r}}}{r^2}\right) \cdot (r^2 d\Omega \hat{\mathbf{r}}) = \oiint_{\partial V} d\Omega = 4\pi, \quad (47)$$

where $d\Omega = \sin\theta d\theta d\phi$ is the angular area element.

We must be careful in our treatment of the case $r = 0$:

$$4\pi\rho(\vec{r}) = \begin{cases} 0, & r \neq 0, \\ \lim_{r \rightarrow 0} \frac{1}{r^2} \frac{\partial(r^2/r^2)}{\partial r} = \infty, & r = 0. \end{cases}$$

Looks familiar? This form is precisely a delta function $\delta^{(3)}(\vec{r})!$ Hence, the actual solution for

the field density is

$$\rho(\vec{r}) = \frac{1}{4\pi} \delta^{(3)}(\vec{r}), \quad (48)$$

which is indeed in agreement with Gauss' law.

Remark We have proven a very important relation,

$$\nabla^2 \left(\frac{1}{r} \right) = -4\pi \delta^{(3)}(\vec{r}). \quad (49)$$

Note that the origin can be displaced to give the general identity

$$\nabla^2 \left(\frac{1}{|\vec{r} - \vec{r}_0|} \right) = -4\pi \delta^{(3)}(\vec{r} - \vec{r}_0). \quad (50)$$