Physics 3A for Electrical Engineering

- Home assignments: Mandatory to submit 10 out of 10-13 that will be published.
- The final grade will be the number of submitted home assignments (up to 10) + 0.9* grade of the final exam.
- Information about the structure of the final exam will be published toward the end of the course.
- Reception hours: Wednesday 14:00-15:00 or as published on the course website.
- My email for questions: bel@bgu.ac.il

Basic Elements of Quantum Theory

- The photoelectric effect
- Waves
- de Broglie wavelength
- Schrodinger equation
- Probability and its relation to the wavefunction
- Expectation values of operators
- Heisenberg uncertainty principle

Recommended literature:

- *Basic Quantum Mechanics*, J. M. Cassels, Chapters 1-3, 7.
- *Introduction to Modern Physics*, J. D. McGervey, Chapters 3-5, 10.
- *Solid State Physics*, N. W. Ashcroft and N. D. Mermin, Chapters 1-5, 8-9.
- Lecture notes by Amir Erez, look for the link on the course web page.

Waves

- Wave is the propagation of dynamic disturbance of a physical quantity.
- A periodic wave is the propagation of a periodic fluctuation in space and time.
- Longitudinal wave – when the oscillation is in the direction of propagation (e.g., sound waves).
- Transverse wave – when the oscillation is perpendicular to the direction of propagation (e.g., surface ocean waves).
- The classical 1D wave equation is

$$\frac{\partial^2 \psi(x,t)}{\partial t^2} = c^2 \frac{\partial^2 \psi(x,t)}{\partial x^2}$$

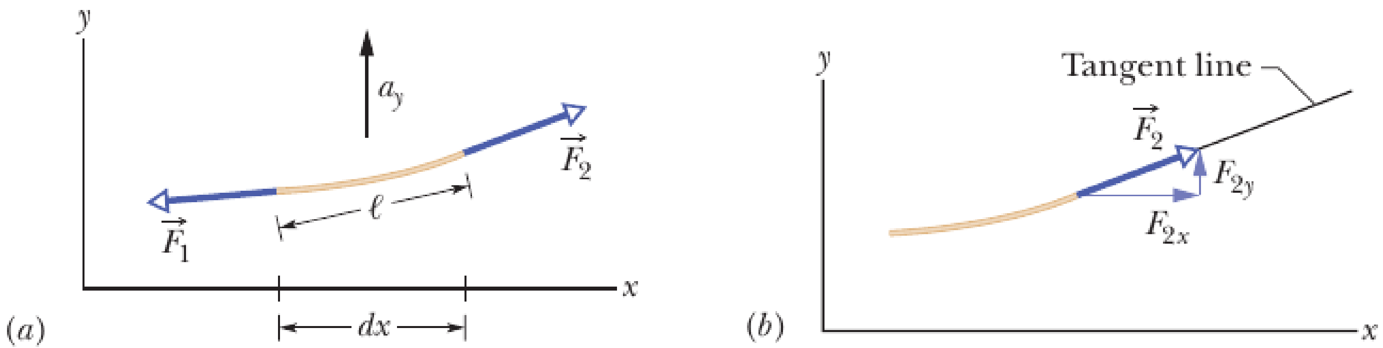
c – is the propagation speed of the wave

Waves on a string

Video

1D-Elastic wave equation

- Consider a string which at rest is along the x-axis.
- When a fluctuation along the y-axis is initiated the string's tension applies forces to each segment of the string.
- Under the assumption of small fluctuations, the dynamics is along the y-axis only.
- Using Newton's law, we can derive the equation of motion for each segment.
- The linear density is $\rho = M/L$, where M is the mass of the entire string and L is its length at rest (parallel to the x-axis).
- The forces at the ends of the segment are, in general, not parallel because of the angle of the string.
- The vertical only motion implies no acceleration in the x-direction.



1D-Elastic wave equation

- Newton's 2[nd] law for the two components reads:

$$(horizontal) \quad T(x,t)cos\big(\theta(x,t)\big) = T(x+\Delta x,t)cos\big(\theta(x+\Delta x,t)\big) = constant = \tau$$

The above equation implies a constant horizontal tension in the string.

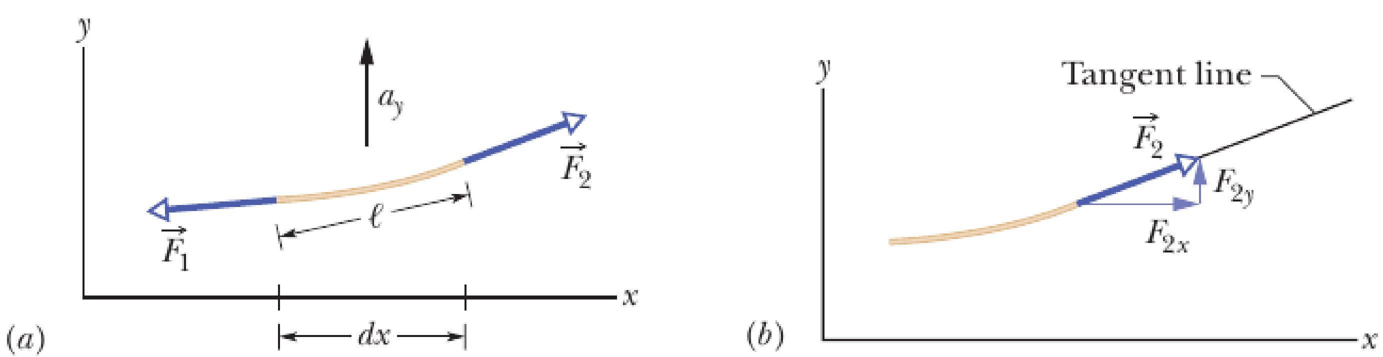
$$(vertical) \quad dm\frac{\partial^2 y}{\partial t^2} = T(x+\Delta x,t)sin\big(\theta(x+\Delta x,t)\big) - T(x,t)sin\big(\theta(x,t)\big)$$

$$= T(x+\Delta x,t)cos\big(\theta(x+\Delta x,t)\big)tan\big(\theta(x+\Delta x,t)\big) - T(x,t)cos\big(\theta(x,t)\big)tan\big(\theta(x,t)\big)$$

$$= \tau\Big(tan\big(\theta(x+\Delta x,t)\big) - tan\big(\theta(x,t)\big)\Big)$$

- Note that $\tan(\theta(x,t)) = \frac{\partial y}{\partial x}$

- $dm\frac{\partial^2 y}{\partial t^2} = \tau\left(\frac{\partial y}{\partial x}(x+\Delta x,t) - \frac{\partial y}{\partial x}(x,t)\right)$



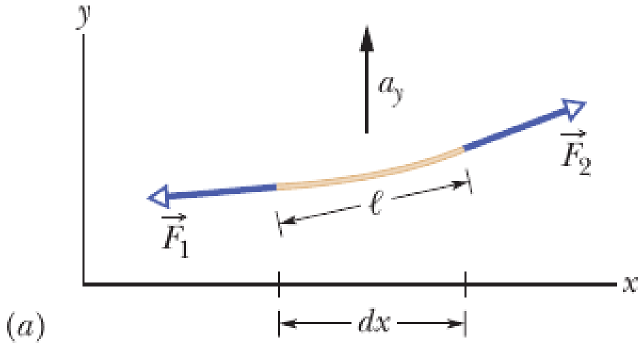
1D-Elastic wave equation

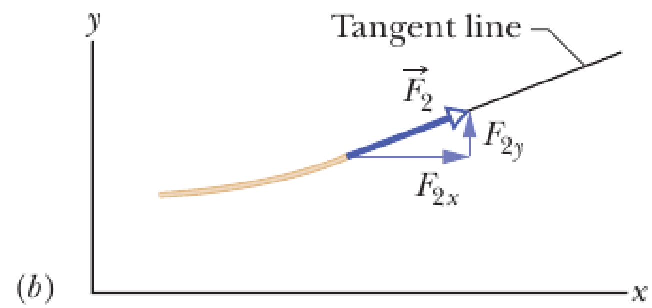
- Restricting ourselves to small angles, i.e., small vertical fluctuations, we may write

$$\rho \Delta x \frac{\partial^2 y}{\partial t^2} = \tau \left(\frac{\partial y}{\partial x}(x + \Delta x, t) - \frac{\partial y}{\partial x}(x, t) \right)$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\tau}{\rho} \frac{\partial^2 y}{\partial x^2}$$

Note that τ has the units of force $[mass \times length/time^2]$, the density has units of $[mass/length]$ so $\frac{\tau}{\rho}$ has the units of $\left[\left(\frac{length}{time}\right)^2\right] = [velocity^2]$.





Waves

- Solution by separation of variables

$$\psi(x,t) = X(x)T(t)$$

$$X(x)\frac{\partial^2 T(t)}{\partial t^2} = c^2 T(t)\frac{\partial^2 X(x)}{\partial x^2}$$

$$\frac{1}{c^2 T(t)}\frac{\partial^2 T(t)}{\partial t^2} = \frac{1}{X(x)}\frac{\partial^2 X(x)}{\partial x^2} = const = -k^2$$

Note that k is independent of x and t, and it has units of 1/length

$$X(x) = A_1 e^{ikx} + A_2 e^{-ikx} \qquad T(t) = B_1 e^{ikct} + B_2 e^{-ikct}$$

$$\psi(x,t) = A_+ \cos(kx - \omega t + \phi_+) + A_- \cos(kx + \omega t + \phi_-)$$

$$\omega = ck$$

The unknown coefficients are determined by the boundary and initial conditions.

The solution is a superposition of waves traveling in the positive and negative directions.

Waves

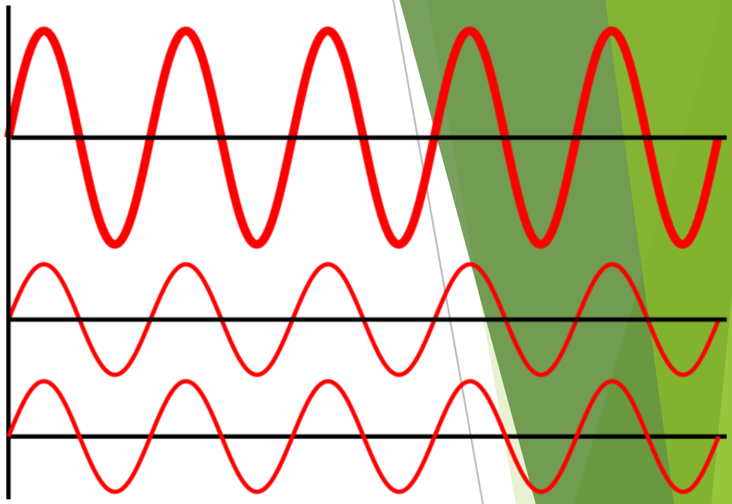
- $\psi(x,t) = A_+ \cos(kx - \omega t + \phi_+) + A_- \cos(kx + \omega t + \phi_-)$
- $\omega = ck$
- The solution is a superposition of waves traveling in the positive and negative directions. Due to the linear nature of the equation the sum of any number of solutions is also a solution (superposition).
- The solution is invariant to time translations by $\tau = \frac{2\pi n}{\omega} = nT$ where $T = \frac{2\pi}{\omega} = 1/\nu$ is the period of the wave.
- The solution is invariant to translations by $l = \frac{2\pi n}{k} = n\lambda$ where $\lambda = 2\pi/k$ is the wavelength.
- k is the wavenumber

$kx \pm \omega t = k(x \pm v_p t)$ so it's clear that the phase velocity is $v_p = \frac{\omega}{k} = c$

Waves

- At a given point in space, two waves may interfere

Constructive (in-phase)



The simplest example for a constructive interference at all points is

$$y(x,t) = Asin(kx - \omega t) + Asin(kx - \omega t + \phi)$$

Using

$$\sin(\alpha) + \sin(\beta) = 2\sin\left(\frac{1}{2}(\alpha+\beta)\right)\cos\left(\frac{1}{2}(\alpha-\beta)\right)$$

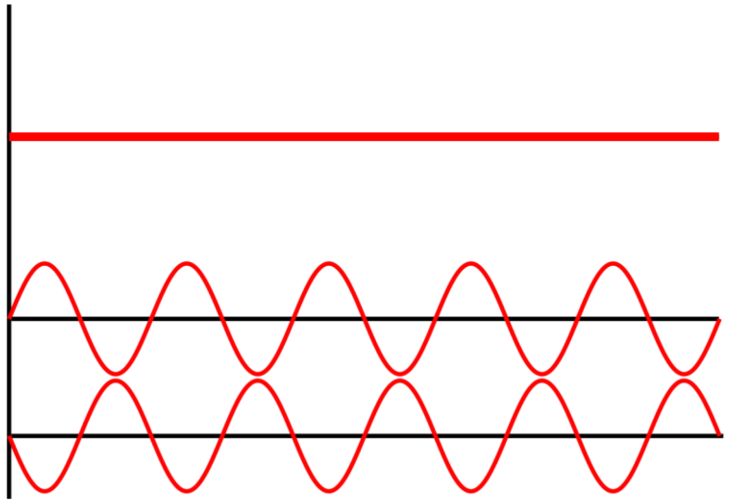
$$y(x,t) = 2Acos\left(\frac{1}{2}\phi\right)sin\left(kx - \omega t + \frac{1}{2}\phi\right) = 2Asin(kx - \omega t)$$

$$\phi = 2\pi n$$

Waves

- At a given point in space, two waves may interfere

Destructive (anti-phase)



The simplest example for a destructive interference at all points is

$$y(x,t) = Asin(kx - \omega t) + Asin(kx - \omega t + \phi)$$

Using

$$\sin(\alpha) + \sin(\beta) = 2\sin\left(\frac{1}{2}(\alpha+\beta)\right)\cos\left(\frac{1}{2}(\alpha-\beta)\right)$$

$$y(x,t) = 2Acos\left(\frac{1}{2}\phi\right)sin\left(kx - \omega t + \frac{1}{2}\phi\right) = 0$$

$$\phi = (2n+1)\pi$$

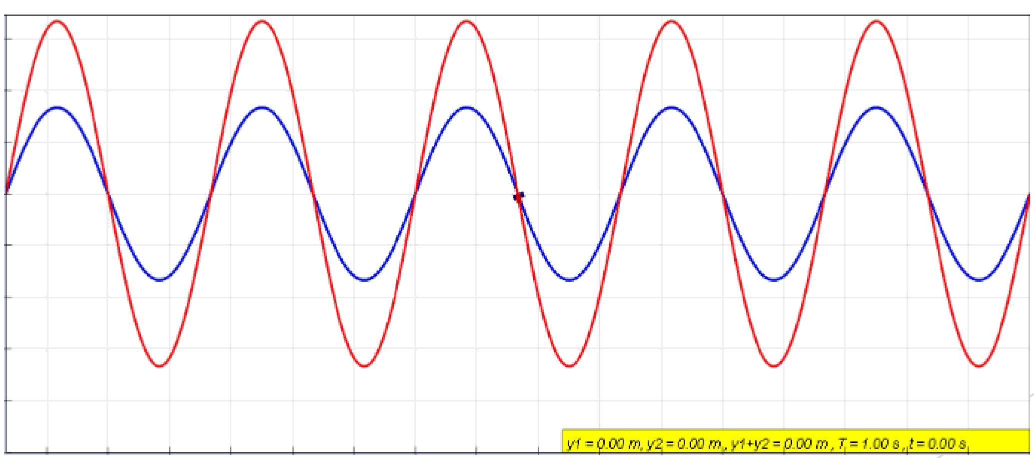
Waves

- Two harmonic waves with the same amplitude, traveling in opposite directions, yield standing waves

$$y(x,t) = Asin\left(k\left(x - \frac{\omega}{k}t\right)\right) + Asin\left(k\left(x + \frac{\omega}{k}t\right)\right)$$

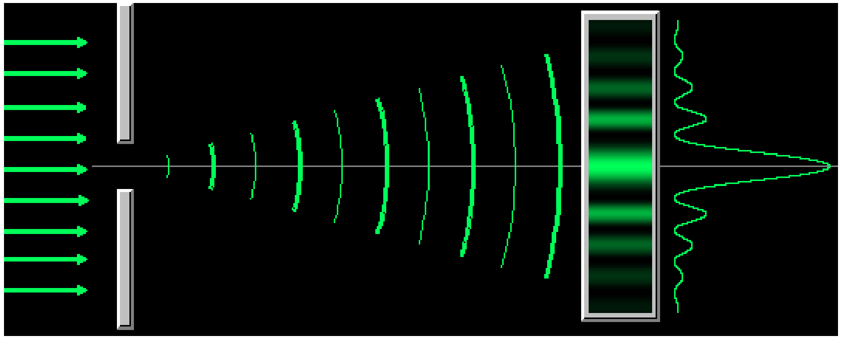
$$\sin(\alpha) + \sin(\beta) = 2\sin\left(\frac{1}{2}(\alpha+\beta)\right)\cos\left(\frac{1}{2}(\alpha-\beta)\right)$$

$$y(x,t) = 2Acos(\omega t)sin(kx)$$

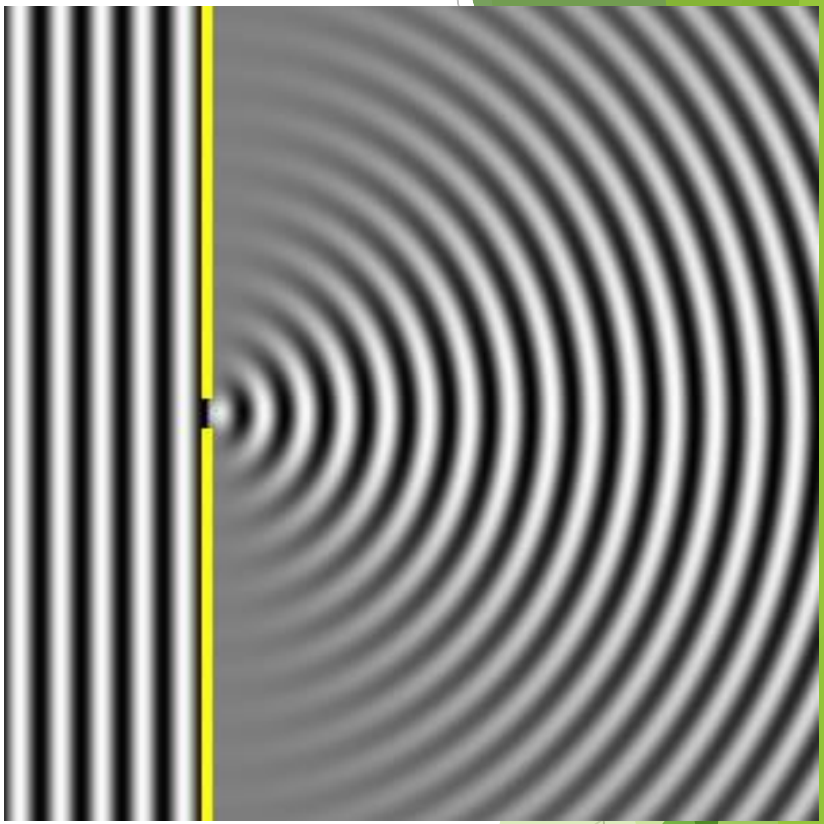


By Lookang many thanks to author of original simulation = Wolfgang Christian and Francisco Esquembre author of Easy Java Simulation = Francisco Esquembre - Own work, CC BY-SA 4.0, https://commons.wikimedia.org/w/index.php?curid=39309437

Light passage through a single slit

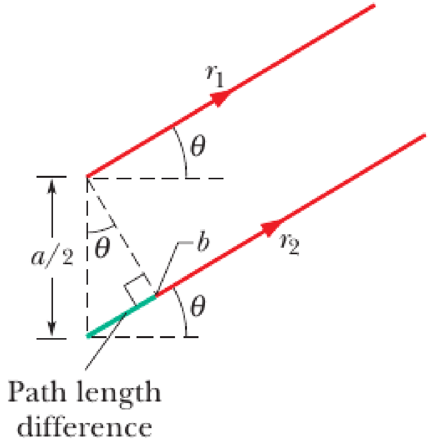


Huygens' principle – every point on a wave front is considered to be a secondary source of spherical wavelets.



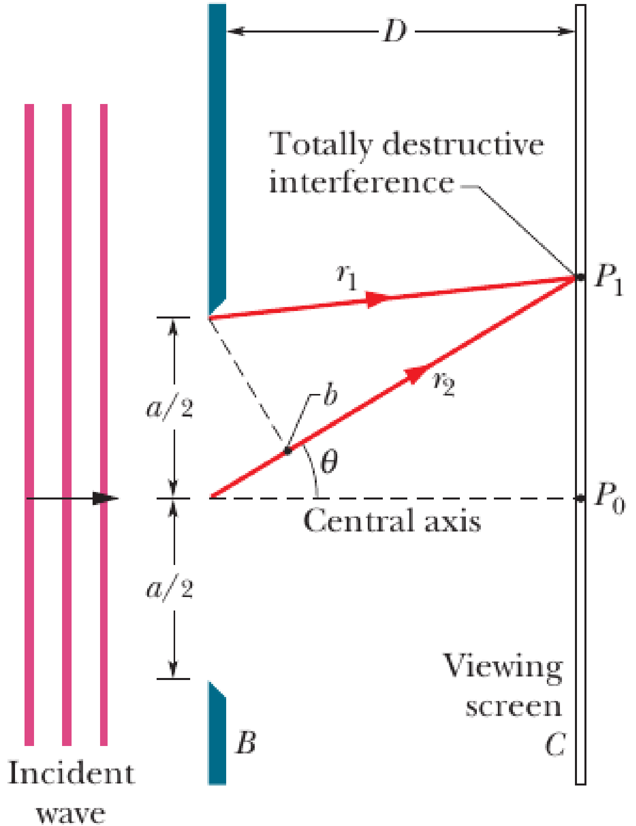
Lookangmany thanks to Fu-Kwun Hwang and author of Easy Java Simulation = Francisco Esquembre / CC BY-SA

Light passage through a single slit



This path length difference shifts one wave from the other, which determines the interference.

This pair of rays cancel each other at P_1. So do all such pairings.



For $D >> a$, we can approximate rays r_1 and r_2 as being parallel, at angle θ to the central axis. The path length difference is then $\frac{a}{2}\sin(\theta)$. The condition for destructive interference is

$\frac{a}{2}\sin(\theta) = \frac{\lambda}{2}$. By repeating a similar analysis we find that the minima are found by

$$\sin(\theta) = \frac{m\lambda}{a}$$